

MATH 4377 - MATH 6308

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1 Chapter 2

- Section 2.3 - Composition of Linear Transformations
- Section 2.4 - Invertibility and Isomorphism
- Section 2.5 - Change of Coordinate Matrix
- Section 2.6 - Dual Spaces

Composition of Linear Transformations and Matrix Multiplication

Section 2.3

Theorem about the composition of linear transformations

Theorem

Let V, W, Z be vector spaces over the same field. Let $T : V \rightarrow W$ and $U : W \rightarrow Z$ be linear. Then $U \circ T : V \rightarrow Z$ is linear.

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Proof.

We want to verify that linearity holds for $U \circ T$:

$$(i) \quad U \circ T(\alpha v) = U(T(\alpha v)) = U(\alpha T(v)) = \alpha U(T(v))$$

(ii)

$$U \circ T(v + v') = U(T(v + v')) = U(T(v) + T(v')) = U(T(v)) + U(T(v'))$$

Theorem

Let $U, S, T : V \rightarrow V$ linear. Then

- $U \circ (S + T) = U \circ S + U \circ T$
- $(U + S) \circ T = U \circ T + S \circ T$
- $U \circ (S \circ T) = (U \circ S) \circ T$
- $I \circ U = U \circ I = U$ (I is the identity)
- $a(U \circ S) = (aU) \circ S = U \circ (aS)$ (a scalar)

Matrix of a composition

Goal: Want to write the matrix representation of $U \circ T$.

Theorem

Let $T : V \rightarrow W$, $U : W \rightarrow Z$ be linear transformations on finite-dimensional vector spaces. Let $\alpha = \{\mathbf{v}_j\}$, $\beta = \{\mathbf{w}_k\}$, $\gamma = \{\mathbf{z}_i\}$ be the ordered basis for V , W , and Z . Then $[U \circ T]_{\alpha}^{\gamma} = [U]_{\beta}^{\gamma} [T]_{\alpha}^{\beta}$.

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Proof.

We can write the matrices $[T]_{\alpha}^{\beta} = (b_{kj})$ and $[U]_{\beta}^{\gamma} = (a_{ik})$. Then

$$\begin{aligned}(U \circ T)(\mathbf{v}_j) &= U(T(\mathbf{v}_j)) = U\left(\sum_k b_{kj} \mathbf{w}_k\right) = \sum_k b_{kj} U(\mathbf{w}_k) \\ &= \sum_k b_{kj} \left(\sum_i a_{ik} \mathbf{z}_i\right) = \sum_i \left(\sum_k a_{ik} b_{kj}\right) \mathbf{z}_i.\end{aligned}$$

Consequently, the matrix representation of $[U \circ T]_{\alpha}^{\gamma}$ is $c_{ij} = \sum_k a_{ik} b_{kj}$.

Definition

Let A be an $m \times n$ matrix and B an $n \times p$ matrix. Define the *matrix product* of A and B to be the $m \times p$ matrix $C = (c_{ij})$ given by

$$(AB)_{ij} = c_{ij} = \sum_{k=1}^n a_{ik} b_{kj}.$$

Ex:

$$\begin{bmatrix} 1 & 2 & 3 \\ 2 & 1 & 1 \end{bmatrix} \begin{bmatrix} 3 \\ 0 \\ 4 \end{bmatrix} =$$

Matrix notation

Let $A = (a_{ij})$ be an $m \times n$ matrix.

We can denote the matrix explicitly as

$$\begin{pmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ \vdots & \vdots & \vdots & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} \end{pmatrix}$$

Sometimes it is useful to represent the matrix in terms of its columns

$$(\mathbf{a}_1 \quad \mathbf{a}_2 \quad \cdots \quad \mathbf{a}_n)$$

Properties of matrix product

Note: the matrix product is not commutative!

Definition

Let $A \in M_{m \times n}$, $B, C \in M_{n \times p}$, $D, E \in M_{q \times m}$. Then

- 1 $A(B + C) = AB + AC$
- 2 $(D + E)A = DA + EA$
- 3 $a(AB) = A(aB) = (aA)B$ (a scalar)
- 4 If V is an n dimensional vector space with ordered basis β , then $[I_V]_\beta = I_n$.
- 5 $I_m A = A I_n$

Theorem

Theorem

Let V, W be finite-dimensional vector spaces with ordered bases β and γ and $T : V \rightarrow W$ be linear. Then $\forall \mathbf{v} \in V$:

$$[T(\mathbf{v})]_{\gamma} = [T]_{\beta}^{\gamma}[\mathbf{v}]_{\beta}.$$

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$$[T(\mathbf{v})]_{\gamma} = [T]_{\beta}^{\gamma} [\mathbf{v}]_{\beta}.$$

Proof. Let $\beta = \{v_1, \dots, v_n\}$ and $\gamma = \{w_1, \dots, w_m\}$.

We can expand any $v \in V$ w.r. to β , so it will be sufficient to examine one basis vector. For J fixed, we can write

$$T(v_J) = \sum_{i=1}^m a_{iJ} w_i$$

Hence

$$[T(v_J)]_{\gamma} = (a_{1J}, \dots, a_{mJ})$$

and

$$[T]_{\beta}^{\gamma} [v_J]_{\beta} = (a_{ij}) e_J = (a_{1J}, \dots, a_{mJ}),$$

where $(a_{ij}) e_J$ is extracting the J -th column of the matrix.

Matrix vector multiplication

Multiplying a $m \times n$ matrix A and a vector $\mathbf{x} \in F^n$ transforms \mathbf{x} into a vector $A\mathbf{x} \in F^m$.

$$\text{Let } A = (\mathbf{a}_1 \quad \mathbf{a}_2 \quad \dots \quad \mathbf{a}_n) \text{ and } \mathbf{x} = \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix}$$

$$A\mathbf{x} = x_1\mathbf{a}_1 + x_2\mathbf{a}_2 + \dots + x_n\mathbf{a}_n$$

showing that $A\mathbf{x}$ is a **linear combination of the columns of A** .

Matrix vector multiplication

Let A be a $m \times n$ matrix, B a $n \times p$ matrix and $\mathbf{x} \in F^p$ a vector.

We use the notation $B = (\mathbf{b}_1 \ \mathbf{b}_2 \ \dots \ \mathbf{b}_p)$

We have that $AB\mathbf{x} = A(B\mathbf{x})$, so that A acts on the n -vector $B\mathbf{x}$

Then

$$B\mathbf{x} = x_1\mathbf{b}_1 + x_2\mathbf{b}_2 + \dots + x_p\mathbf{b}_p$$

and

$$AB\mathbf{x} = x_1A\mathbf{b}_1 + x_2A\mathbf{b}_2 + \dots + x_pA\mathbf{b}_p = (A\mathbf{b}_1 \ A\mathbf{b}_2 \ \dots \ A\mathbf{b}_p) \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix}$$

Hence $AB = (A\mathbf{b}_1 \ A\mathbf{b}_2 \ \dots \ A\mathbf{b}_p)$, showing that:

each column of AB is a linear combination of the columns of A using weights from the corresponding columns of B .

Definition

Let $A \in M_{m \times n}(F)$. Define $L_A : F^n \rightarrow F^m$ by

$$L_A(\mathbf{x}) = A\mathbf{x},$$

where $\mathbf{x} \in F_n$ is a column vector.

L_A is the **left-multiplication transformation** given by the matrix A .

Theorem

Let A, B be $m \times n$ matrix and β, γ be the standard ordered bases of F^n and F^m , then:

- 1 $L_A : F^n \rightarrow F^m$ is linear.
- 2 $[L_A]_{\beta}^{\gamma} = A$
- 3 $L_A = L_B \Leftrightarrow A = B$
- 4 $L_{A+B} = L_A + L_B$,
- 5 $L_{aA} = aL_A \quad a \in F$
- 6 For $T : F^n \rightarrow F^m$, there exists a unique $m \times n$ matrix C such that $T = L_C$ and $[T]_{\beta}^{\gamma} = C$.
- 7 If $m = n$, then $L_{I_n} = I_{F_n}$

Invertibility and Isomorphism

Section 2.4

Definition

Let V, W be vector spaces. Let $T : V \rightarrow W$ linear. We define $U : W \rightarrow V$ to be the *inverse* of T if $T \circ U = I_W$ and $U \circ T = I_V$. If T has an inverse, T is called *invertible*.

Definition

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Remarks about continuous functions from Appendix B:

- If f has an inverse, the inverse is unique. We write f^{-1} for it.
- Given sets A, B , a function $f : A \rightarrow B$ is invertible if and only if f is one-to-one and onto.

This observation applies to linear transformations.

Example

Let $T : P_1(\mathbb{R}) \rightarrow \mathbb{R}^2$ be defined as $T(a + bx) = (a, a + b)$. Verify that:

$$T^{-1} : \mathbb{R}^2 \rightarrow P_1(\mathbb{R}), \quad T^{-1}(c, d) = c + (d - c)x$$

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SOLUTION.

$$(i) \quad (T^{-1} \circ T)(a + bx) = T^{-1}(T(a + bx)) = T^{-1}(a, a + b) = a + (a + b - a)x = a + bx$$

$$(ii) \quad (T \circ T^{-1})(c, d) = T(T^{-1}(c, d)) = T(c + (d - c)x) = (c, c + d - c) = (c, d)$$

Theorem

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If $T : V \rightarrow W$ is linear and invertible, then the inverse T^{-1} is linear also.

Theorem

If $T : V \rightarrow W$ is linear and invertible, then the inverse T^{-1} is linear also.

Proof.

(i) For $v \in V$, let $T(v) = w$. For $c \in F$,

$$T^{-1}(cw) = T^{-1}(cT(v)) = T^{-1}(T(cv)) = cv = cT^{-1}(w).$$

(ii) For $v_1, v_2 \in V$, let $T(v_1) = w_1$, $T(v_2) = w_2$.

$$\begin{aligned} T^{-1}(w_1 + w_2) &= T^{-1}(T(v_1) + T(v_2)) = T^{-1}(T(v_1 + v_2)) = v_1 + v_2 \\ &= T^{-1}(w_1) + T^{-1}(w_2). \end{aligned}$$

Lemma

Lemma

Let $T : V \rightarrow W$ linear and invertible. Let V, W be finite dimensional.
Then

$$\dim V = \dim W.$$

Lemma

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$$\dim V = \dim W.$$

Proof.

Since T is invertible, it is one-to-one and onto, hence $\text{nullity}(T) = 0$ and $\text{rank}(T) = \dim W$.

By the dimension theorem,

$$\text{nullity}(T) + \text{rank}(T) = \dim V.$$

This implies that $\dim W = \text{rank}(T) = \dim V$.

Definition

Let A be an $n \times n$ matrix. Say A is *invertible* if there exists an $n \times n$ matrix B such that

$$AB = I_n = BA.$$

Remark: Such a B is unique, if it exists. Thus, we can write A^{-1} for B .

Recall

Provided $ad - cb \neq 0$:

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix}^{-1} = \frac{1}{ad - cb} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$$

Ex: Given

$$A = \begin{bmatrix} 1 & 4 \\ 2 & 9 \end{bmatrix},$$

find A^{-1} .

Theorem

Theorem

Let V, W be finite dimensional vector spaces with ordered bases β, γ respectively. Let $T : V \rightarrow W$ linear. Then T is invertible if and only if $[T]_{\beta}^{\gamma}$ is an invertible matrix.

Moreover, in this case, $[T^{-1}]_{\gamma}^{\beta} = ([T]_{\beta}^{\gamma})^{-1}$.

Theorem

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Proof.

The transformation $T : V \rightarrow W$ has matrix representation $[T]_{\beta}^{\gamma}$. If T is invertible, then it is a linear transformation $T^{-1} : W \rightarrow V$ with matrix representation $[T^{-1}]_{\gamma}^{\beta}$. This also implies that $[T^{-1}]_{\gamma}^{\beta} = ([T]_{\beta}^{\gamma})^{-1}$, so that the matrix $[T]_{\beta}^{\gamma}$ is invertible.

Converse direction is left for exercise.

Corollary

Let V be a finite dimensional vector spaces with ordered basis β respectively. Let $T : V \rightarrow V$ linear. Then T is invertible if and only if $[T]_{\beta}$ is an invertible matrix.

Moreover, in this case, $[T^{-1}]_{\beta} = ([T]_{\beta})^{-1}$.

Corollary

An $n \times n$ matrix A is invertible if and only if L_A is invertible and, in this case, $(L_A)^{-1} = L_{A^{-1}}$.

Definition

Let V, W be vector spaces. Say V is *isomorphic* to W if and only if there exists $T : V \rightarrow W$ linear and invertible.

Such a T is called an *isomorphism* from V onto W .

Remark: The property of being isomorphic is an equivalence relation on the set of vector spaces over a given field.

Informally, a vector space V is isomorphic to W if every vector space calculation in V is accurately reproduced in W , and vice versa.

Theorem

Theorem

Let V, W be finite dimensional vector spaces (over the same field). Then V is isomorphic to W if and only if $\dim V = \dim W$.

Proof for \Rightarrow This was proved by Lemma in slide 23.

Proof for \Leftarrow Suppose $\dim V = \dim W$. We need to show that there exists a linear and invertible map $T : V \rightarrow W$.

Let $B = \{v_1, \dots, v_n\}$ be a basis of V and $G = \{w_1, \dots, w_n\}$ a basis of W . We define a linear transformation $T : V \rightarrow W$ by $T(v_i) = w_i$, for $i = 1, \dots, n$.

Since $\text{span}\{T(v_i) : i = 1, \dots, n\} = \text{span}\{w_i : i = 1, \dots, n\} = W$, then T is onto.

By the Dimension Theorem, $\text{nullity}(T) + \text{rank}(T) = \dim V$ implying that $\text{nullity}(T) + \dim W = \dim V$ so that $\text{nullity}(T) = 0$. This implies that T is one-to-one.

Since T is one-to-one and onto, it is invertible.

Corollary

Let V be a vector space over F . Then V is isomorphic to F^n if and only if $\dim V = n$.

Examples of vector space isomorphic to \mathbb{R}^n :

- 1 P_{n-1} the set of polynomial of degree at most $n - 1$
- 2 $M^{p \times q}$, $pq = n$, the class $p \times q$ matrices where $pq = n$.

In these examples one can construct an invertible linear map from \mathbb{R}^n into these spaces.

Theorem

Theorem

Let V, W be finite dimensional vector spaces over F . Let $\dim V = n$, $\dim W = m$. Let β, γ be ordered bases for V and W . Then

$$\Phi : \mathcal{L}(V, W) \rightarrow M_{m \times n}(F)$$

is an isomorphism.

Proof. We need to show that Φ is an isomorphism.

A direct argument shows that Φ is linear. In fact, for any $T, U \in \mathcal{L}(V, W)$, with matrix representations $[T]_{\beta}^{\gamma}$ and $[U]_{\beta}^{\gamma}$, respectively, where $\beta = \{v_1, \dots, v_n\}$ is a basis of V and $\gamma = \{w_1, \dots, w_m\}$ a basis of W , we have that

$$[T + U]_{\beta}^{\gamma} = [T]_{\beta}^{\gamma} + [U]_{\beta}^{\gamma}$$

$$[cT]_{\beta}^{\gamma} = c[T]_{\beta}^{\gamma}$$

We also need to show that Φ is invertible.

The nullspace is $N(\Phi) = \{T : V \rightarrow W : [T]_{\beta}^{\gamma} = 0^{m \times n}\}$ and consists of the linear transformations mapping every vector to the 0 vector. This space contains only the transformation mapping every vector to 0, hence Φ is one-to-one.

For every matrix $A = [a_{ij}]$, $A \in M^{m \times n}$ we can construct the linear transformation

$$T(v_j) = \sum_{i=1}^m a_{ij} w_i, \quad j = 1, \dots, n$$

showing that Φ is onto.

Since Φ is one-to-one and onto, it is invertible.

Remark: $\dim \mathcal{L}(V, W) = \dim M_{m \times n} = n \cdot m = (\dim V) \cdot (\dim W)$.

The standard representation

Definition

let β be an ordered basis for an n -dimensional vector space V over the field F . The standard representation of V with respect to β is the function

$$\phi_\beta : V \rightarrow F^n$$

given by $\phi_\beta(x) = [x]_\beta$.

Theorem

For any finite dimensional vector space V with ordered basis β , the map ϕ_β is an isomorphism.

The standard representation

Example.

Let $\beta = \{b_1, b_2\}$ where $b_1 = (3, 3, 1)$, $b_2 = (0, 1, 3)$.

Let $H = \text{span}\{b_1, b_2\}$. Find the standard representation of H with respect to β for $x = (9, 13, 15)$.

We need to find c_1, c_2 such that $x = c_1 b_1 + c_2 b_2$.

Solving the equation, we find $\phi_\beta(x) = [x]_\beta$.

The Change of Coordinate Matrix

Section 2.5

Theorem

Let β, β' be ordered bases for the finite-dimensional vector space V . Let $Q = [I_V]_{\beta'}^{\beta}$. Then

- 1 Q is invertible
- 2 $\forall \mathbf{v} \in V : [\mathbf{v}]_{\beta} = Q[\mathbf{v}]_{\beta'}$.

Remark: Q is called the *change of coordinates matrix*. It changes β' -coordinates to β -coordinates.

Theorem

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- 1 Q is invertible
- 2 $\forall \mathbf{v} \in V : [\mathbf{v}]_{\beta} = Q[\mathbf{v}]_{\beta'}$.

Remark: Q is called the *change of coordinates matrix*. It changes β' -coordinates to β -coordinates.

Proof. (1) Q is one-to-one since $N(Q) = \{0\}$ and it is one onto since for any v in the β basis we can find a v in the β' basis.

$$(2) [T(\mathbf{v})]_{\gamma} = [T]_{\beta}^{\gamma}[\mathbf{v}]_{\beta}$$

$$\text{Also } [I_V(\mathbf{v})]_{\beta} = [I_V]_{\beta'}^{\beta}[\mathbf{v}]_{\beta'}$$

$$\text{Hence } [\mathbf{v}]_{\beta} = [I_V]_{\beta'}^{\beta}[\mathbf{v}]_{\beta'}$$

Example

Let $\beta' = \{(2, 4), (3, 1)\} := \{v_1, v_2\}$, $\beta = \{(1, 1), (1, -1)\}$. Find the change of coordinates matrix $Q = [I_V]_{\beta'}^{\beta}$.

Example

Let $\beta' = \{(2, 4), (3, 1)\} := \{v_1, v_2\}$, $\beta = \{(1, 1), (1, -1)\}$. Find the change of coordinates matrix $Q = [I_V]_{\beta'}^{\beta}$.

SOLUTION:

$$I(v_1) = (2, 4) = a_1(1, 1) + a_2(1, -1) = (a_1 + a_2, a_1 - a_2)$$

Solving the system, one finds $a_1 = 3, a_2 = -1$

$$I(v_2) = (3, 1) = b_1(1, 1) + b_2(1, -1) = (b_1 + b_2, b_1 - b_2)$$

Solving the system, one finds $b_1 = 2, b_2 = 1$

Thus, we have that $Q = \begin{pmatrix} 3 & 2 \\ -1 & 1 \end{pmatrix}$

Question

Let $T : V \rightarrow V$ linear.

What is the relationship between $[T]_{\beta}$ and $[T]_{\beta'}$?

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Let $T : V \rightarrow V$ linear.

What is the relationship between $[T]_{\beta}$ and $[T]_{\beta'}$?

Recall that if $T : V \rightarrow V$ with basis β for both domain and codomain then the matrix representation of T is $[T]_{\beta}^{\beta} = [T]_{\beta}$

Theorem

Theorem

Let $T : V \rightarrow V$ linear with V finite dimensional vector space. Let β, β' be ordered bases for V . Let $Q = [I_V]_{\beta'}^{\beta}$. Then

$$[T]_{\beta'} = Q^{-1}[T]_{\beta}Q.$$

Theorem

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$$[T]_{\beta'} = Q^{-1}[T]_{\beta}Q.$$

Idea of Proof

$$[T]_{\beta'}^{\beta'} = [I_V]_{\beta'}^{\beta} [T]_{\beta}^{\beta} [I_V]_{\beta}^{\beta'}$$

Example

Let $\beta = \{(1, 1), (1, -1)\}$, $\beta' = \{(2, 4), (3, 1)\}$. Knowing that

$$[T]_{\beta} = \begin{pmatrix} 3 & 1 \\ -1 & 3 \end{pmatrix},$$

find $[T]_{\beta'}$.

Example

Let $\beta = \{(1, 1), (1, -1)\}$, $\beta' = \{(2, 4), (3, 1)\}$. Knowing that

$$[T]_{\beta} = \begin{pmatrix} 3 & 1 \\ -1 & 3 \end{pmatrix},$$

find $[T]_{\beta'}$.

SOLUTION:

From prior example, we have that the change of variables matrix is

$$Q = \begin{pmatrix} 3 & 2 \\ -1 & 1 \end{pmatrix}.$$

By theorem above, $[T]_{\beta'} = Q^{-1}[T]_{\beta}Q$.

We compute $Q^{-1} = \frac{1}{3+2} \begin{pmatrix} 1 & -2 \\ 1 & 3 \end{pmatrix} = \begin{pmatrix} 1/5 & -2/5 \\ 1/5 & 3/5 \end{pmatrix}$.

Therefore:

$$[T]_{\beta'} = Q^{-1}[T]_{\beta}Q = \begin{pmatrix} 1/5 & -2/5 \\ 1/5 & 3/5 \end{pmatrix} \begin{pmatrix} 3 & 1 \\ -1 & 3 \end{pmatrix} \begin{pmatrix} 3 & 2 \\ -1 & 1 \end{pmatrix}$$

Solving the matrix multiplication, we find

$$[T]_{\beta'} = \begin{pmatrix} 4 & 1 \\ -2 & 2 \end{pmatrix}$$

Definitions

Let $A, B \in M_{n \times n}(F)$. We say B is *similar* to A if and only if there exists an invertible $Q \in M_{n \times n}(F)$:

$$B = Q^{-1}AQ.$$

Remark: Being similar is an equivalence relation on $M_{n \times n}(F)$.

Dual Spaces

Section 2.6

Definition

Let V be a vector space over the field F . A linear transformation $f : V \rightarrow F$, where F is considered as a vector space over itself, is called a *linear functional*.

Examples:

1. $f : \mathbb{R}^n \rightarrow \mathbb{R}, (x_1, \dots, x_n) \mapsto x_1$
2. $f : \mathbb{R}^2 \rightarrow \mathbb{R}, (x_1, x_2) \mapsto 2x_1 - 3x_2$
3. $f : \mathbb{R}^n \rightarrow \mathbb{R}, (x_1, \dots, x_n) \mapsto x_1 + \dots + x_n$

More examples

- $\text{tr} : M_{n \times n} \rightarrow \mathbb{R}, A \mapsto \text{tr}(A)$
- $\text{eval}_5 : \{g : \mathbb{R} \rightarrow \mathbb{R}\} \rightarrow \mathbb{R}, g \mapsto g(5).$
- Let V be a vector space over F , $\beta = \{\mathbf{v}_1, \dots, \mathbf{v}_n\}$ ordered basis. Let $f_i : V \rightarrow F$ be defined by:
 $f_i(\mathbf{v}) =$ the i -th coordinate of \mathbf{v} with respect to β .
In other words, if $[\mathbf{v}]_\beta = (a_1, \dots, a_n)$, then $f_i(\mathbf{v}) = a_i$. In particular, $f_i(\mathbf{v}_j) = \delta_{ij}$.

Example

Let $V = \mathbb{R}^2$. Let $\beta = \{(2, 1), (3, 1)\} := \{v_1, v_2\}$. Find f_1, f_2 .

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SOLUTION.

For $v \in \mathbb{R}^2$, $[v]_\beta = (a_1, a_2)$ and $f_1(v) = a_1, f_2(v) = a_2$.

$$(x, y) = a_1(2, 1) + a_2(3, 1) = (2a_1 + 3a_2, a_1 + a_2)$$

Solving the linear system, we obtain:

$$a_1 = -x + 3y, a_2 = x - 2y$$

Thus:

$$f_1(v) = -x + 3y, f_2(v) = x - 2y$$

Example

Given $f_1(x, y) = -x + 3y$ and $f_2(x, y) = x - 2y$, find $\beta = (v_1, v_2) \subset \mathbb{R}^2$.

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Given $f_1(x, y) = -x + 3y$ and $f_2(x, y) = x - 2y$, find $\beta = (v_1, v_2) \subset \mathbb{R}^2$.

SOLUTION.

We can write any $v = (x, y) \in \mathbb{R}^2$ as

$$v = f_1 v_1 + f_2 v_2$$

If we choose $f_1 = 1, f_2 = 0$, then $v_1 = f_1 v_1$ yielding the system of equations

$$\begin{aligned} -x + 3y &= 1 \\ x - 2y &= 0 \end{aligned}$$

with solution $x = 2, y = 1$, so that we obtain $v_1 = (2, 1)$.

Similarly, choosing $f_1 = 0, f_2 = 1$, then $v_2 = f_2 v_2$ yielding the system of equations

$$\begin{aligned} -x + 3y &= 0 \\ x - 2y &= 1 \end{aligned}$$

with solution $x = 3, y = 1$, so that we obtain $v_2 = (3, 1)$.

Definition

For a vector space V over F , let the *dual space* V^* be $\mathcal{L}(V, F)$.

Remark: For a finite-dimensional V

$$\dim V^* = \dim \mathcal{L}(V, F) = \dim V \cdot \dim F = \dim V$$

This means that V and V^* are isomorphic as vector spaces over F . Also, we can define V^{**} as the dual of V^* .

Theorem

Theorem

Let V be a vector space and $\beta = \{\mathbf{v}_1, \dots, \mathbf{v}_n\}$ ordered basis. Let f_i be the i -th coordinate function with respect to β , as defined above.

Then $\beta^* = \{f_1, \dots, f_n\}$ is an ordered basis for V^* and for all $g \in V^*$,

$$g(\mathbf{v}) = \sum_{i=1}^n g(\mathbf{v}_i) f_i.$$

Definition

We call β^* the *dual basis* of β .